

The NKM with a Supply Shock: Matrix Representation

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The New Keynesian Model with a supply shock

The linearized baseline version of the NKM with supply shocks can be written with 7 equations:

IS :
$$\hat{y}_t = \mathbb{E}_t \hat{y}_{t+1} - \frac{1}{\sigma} (i_t - \mathbb{E}_t \pi_{t+1} - r^n)$$

Taylor rule :
$$i_t = \pi_t + r^n + \phi_\pi (\pi_t - \pi^T) + \phi_y \cdot \hat{y}_t$$

AS :
$$\pi_t = \kappa \cdot \hat{y}_t + \beta \cdot \mathbb{E}_t \pi_{t+1} + s_t$$

Supply shock :
$$s_t = \rho_s s_{t-1} + \varepsilon_t^s \quad , \quad \varepsilon_t^s \sim \mathcal{N}(0, 1)$$

Output allocation :
$$\hat{y}_t = \hat{c}_t$$

Labor supply :
$$\hat{l}_t = \left(\frac{1-\sigma}{1+\gamma} \right) \hat{y}_t$$

Technology :
$$\hat{a}_t = \left[1 - \frac{\alpha(1-\sigma)}{1+\gamma} \right] \hat{y}_t$$

Variables and parameters

- **Endogenous variables:** $\{\hat{y}, \pi, i, \hat{c}, s, \hat{\ell}, \hat{a}\}$ are, respectively, the output-gap, inflation, nominal interest rate, the consumption-gap, supply shock, labor supply, and technology.
- **Exogenous variables:** $\{r^n, \pi^T, \varepsilon\}$, which represent, respectively, the natural level of the real interest rate, the target inflation rate, and a random disturbance.
- **Parameters:** $\{\sigma, \phi_\pi, \phi_y, \kappa = \frac{\psi(1-\mu)(1-\mu\beta)}{\mu}, \psi, \beta, \mu, \rho_s, \alpha, \gamma\}$
- **Forward-looking variables:** \hat{y}_t, π_t
- **Backward-looking variables:** s_t
- **Static variables:** $i_t, \hat{\ell}_t, \hat{a}_t, \hat{c}_t$

4 equations vs 4 unknowns

- The model can be fully simulated only with 4 equations and 4 unknowns:

Supply shock : $s_{t+1} = \rho_s s_t + \varepsilon_{t+1}^s$

Taylor rule : $i_{t+1} = \pi_{t+1} + r^n + \phi_\pi(\pi_{t+1} - \pi^T) + \phi_y \cdot \hat{y}_{t+1}$

AS : $\pi_t = \kappa \cdot \hat{y}_t + \beta \cdot \mathbb{E}_t \pi_{t+1} + s_t$

IS : $\hat{y}_t = \mathbb{E}_t \hat{y}_{t+1} - \frac{1}{\sigma} (i_t - \mathbb{E}_t \pi_{t+1} - r^n)$

- The first two are non-forward looking variables, and the last two are forward looking variables.
- To separate the two blocks of equations, the order we write them matters:
 - First write down the non-forward looking block
 - Then write down the forward looking block

Matrix representation

- The 4 equations can be written as:

$$1s_{t+1} + 0i_{t+1} + 0\mathbb{E}_t\pi_{t+1} + 0\mathbb{E}_t\hat{y}_{t+1} = \rho_s s_t + 0i_t + 0\pi_t + 0\hat{y}_t + 1\varepsilon_{t+1}^s$$

$$0s_{t+1} + 1i_{t+1} - (1 + \phi_\pi)\mathbb{E}_t\pi_{t+1} - \phi_y\mathbb{E}_t\hat{y}_{t+1} = 0s_t + 0i_t + 0\pi_t + 0\hat{y}_t + 0\varepsilon_{t+1}^i + r^n - \phi_\pi\pi^T$$

$$0s_{t+1} + 0i_{t+1} + \beta\mathbb{E}_t\pi_{t+1} + 0\mathbb{E}_t\hat{y}_{t+1} = -1s_t + 0i_t + 1\pi_t - \kappa\hat{y}_t + 0\varepsilon_{t+1}^\pi$$

$$0s_{t+1} + 0i_{t+1} + (1/\sigma)\mathbb{E}_t\pi_{t+1} + 1\mathbb{E}_t\hat{y}_{t+1} = 0s_t + (1/\sigma)i_t + 0\pi_t + 1\hat{y}_t + 0\varepsilon_{t+1}^y + (1/\sigma)r^n$$

- Passing the equations into matrices gives:

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -(1 + \phi_\pi) & -\phi_y \\ 0 & 0 & \beta & 0 \\ 0 & 0 & \frac{1}{\sigma} & 1 \end{bmatrix}}_A \underbrace{\begin{bmatrix} s_{t+1} \\ i_{t+1} \\ \mathbb{E}_t\pi_{t+1} \\ \mathbb{E}_t\hat{y}_{t+1} \end{bmatrix}}_B = \underbrace{\begin{bmatrix} \rho_s & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & -\kappa \\ 0 & \frac{1}{\sigma} & 0 & 1 \end{bmatrix}}_B \underbrace{\begin{bmatrix} s_t \\ i_t \\ \pi_t \\ \hat{y}_t \end{bmatrix}}_B + \underbrace{\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_C \underbrace{\begin{bmatrix} \varepsilon_{t+1}^s \\ \varepsilon_{t+1}^i \\ \varepsilon_{t+1}^\pi \\ \varepsilon_{t+1}^y \end{bmatrix}}_C + \underbrace{\begin{bmatrix} 0 \\ r^n - \phi_\pi\pi^T \\ 0 \\ (1/\sigma)r^n \end{bmatrix}}_D$$

The model is ready for the computer